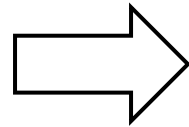
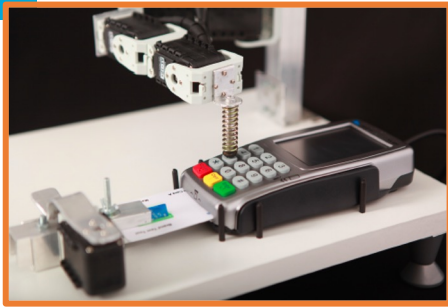


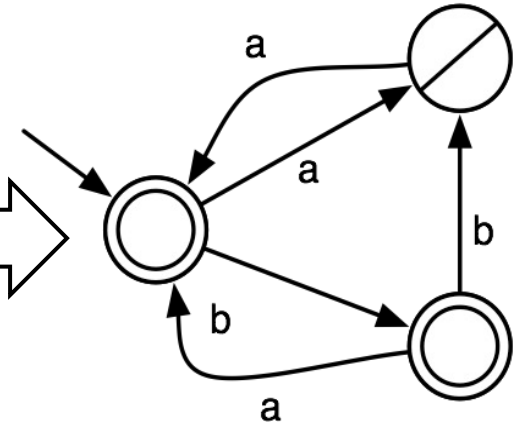
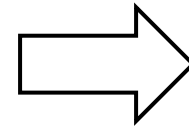


# State machine learning in Flexfringe

# Passive Model Learning



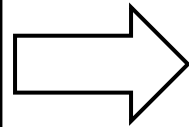
Learning  
Algorithm



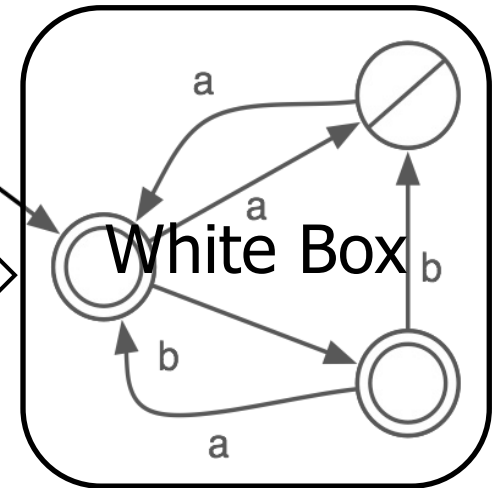
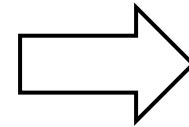
- Software leaves **traces (logs)**
- A state machine is a **logical model** describing these traces
  - Classification – is a new trace generated by the same software?
  - Prediction – what trace is most likely to occur next?
  - **Analysis** – is the software deadlock-free, secure, **malicious**?

# Passive Model Learning

Black Box

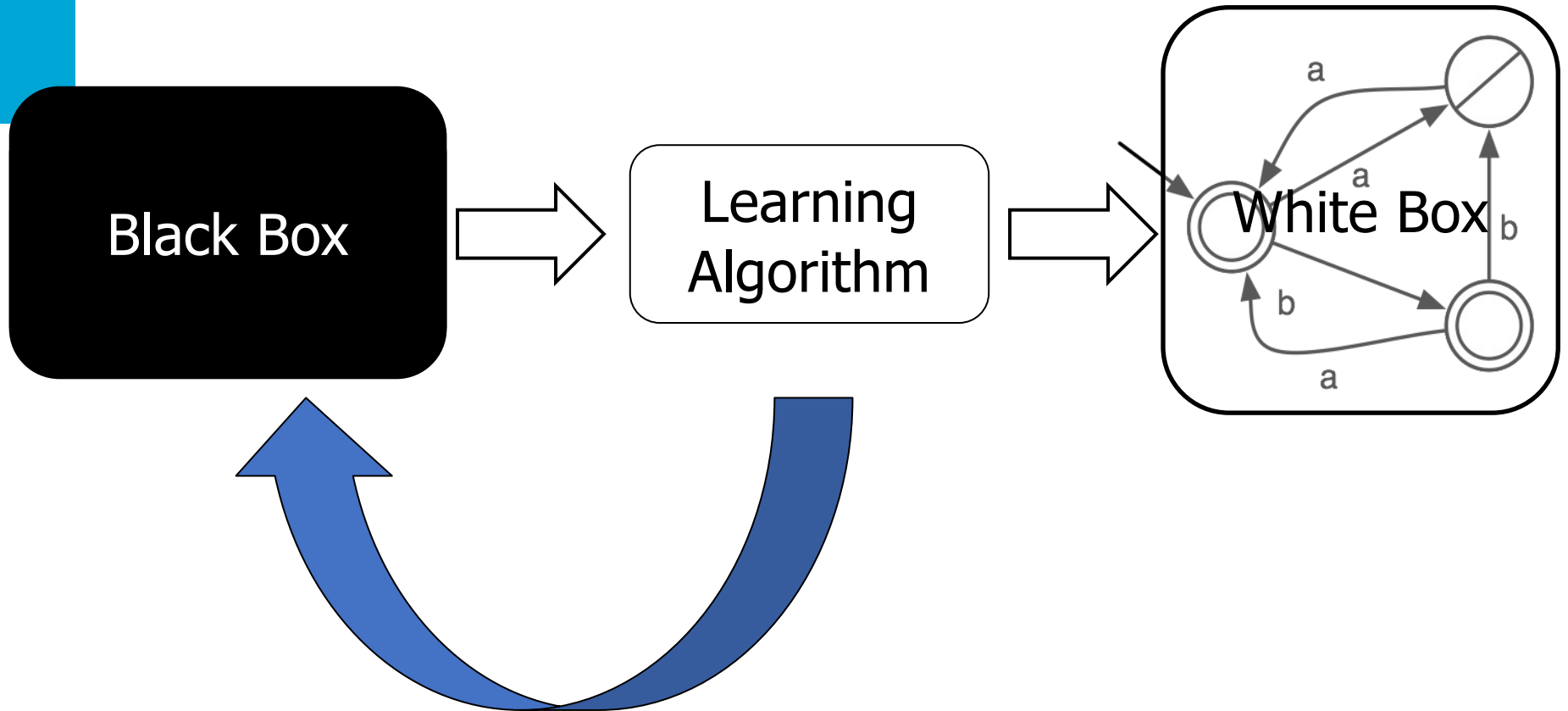


Learning Algorithm

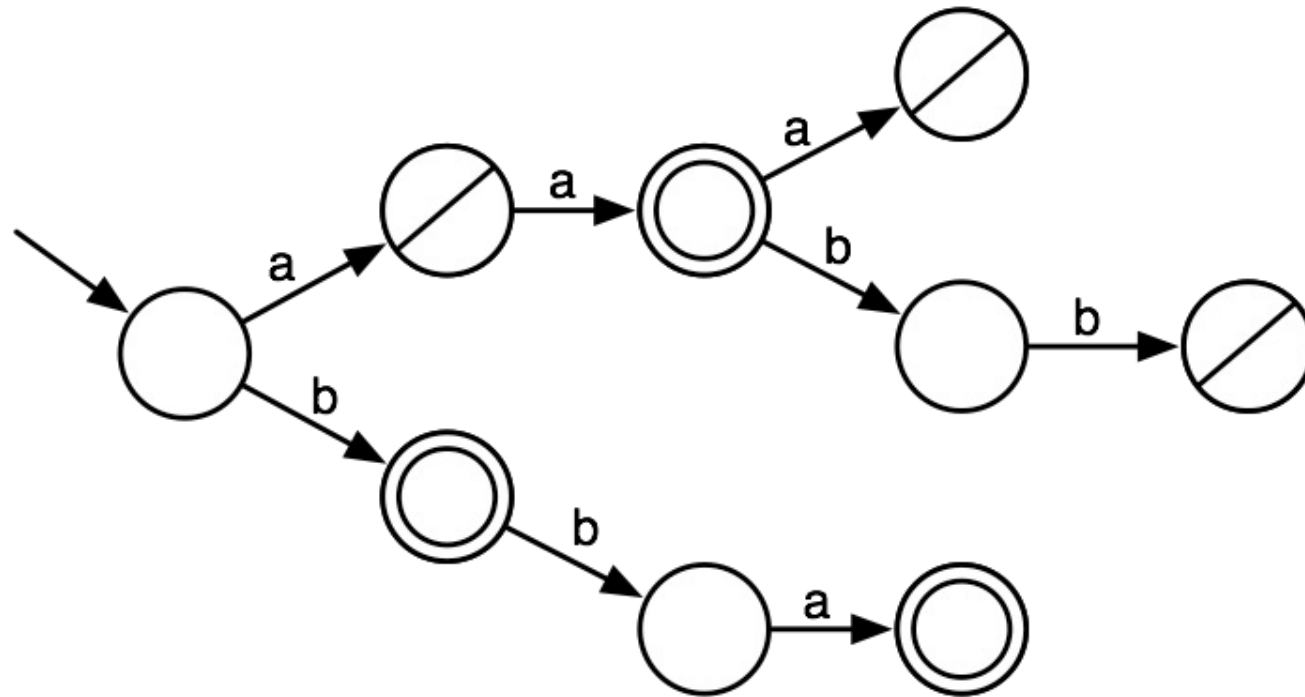


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# Active Model Learning

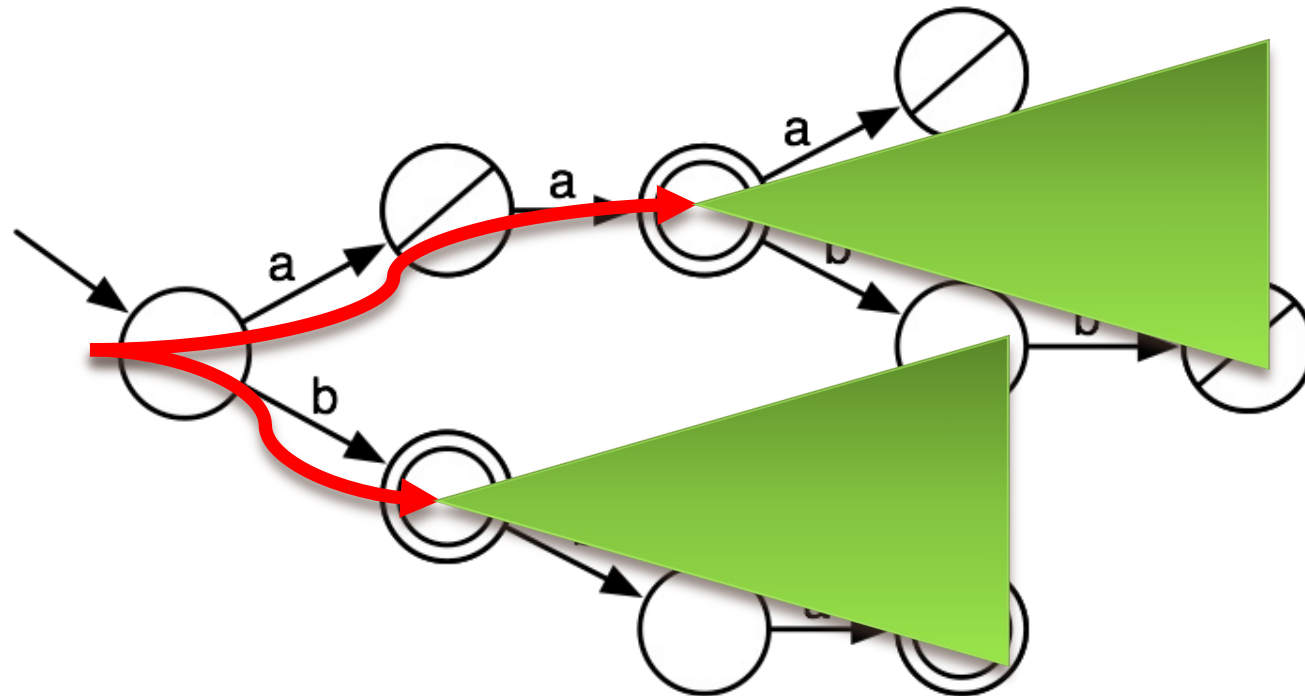


# Learning DFAs



positive data: aa, b, bba; negative data: a, aaa, aabb  
represented as a **prefix tree**

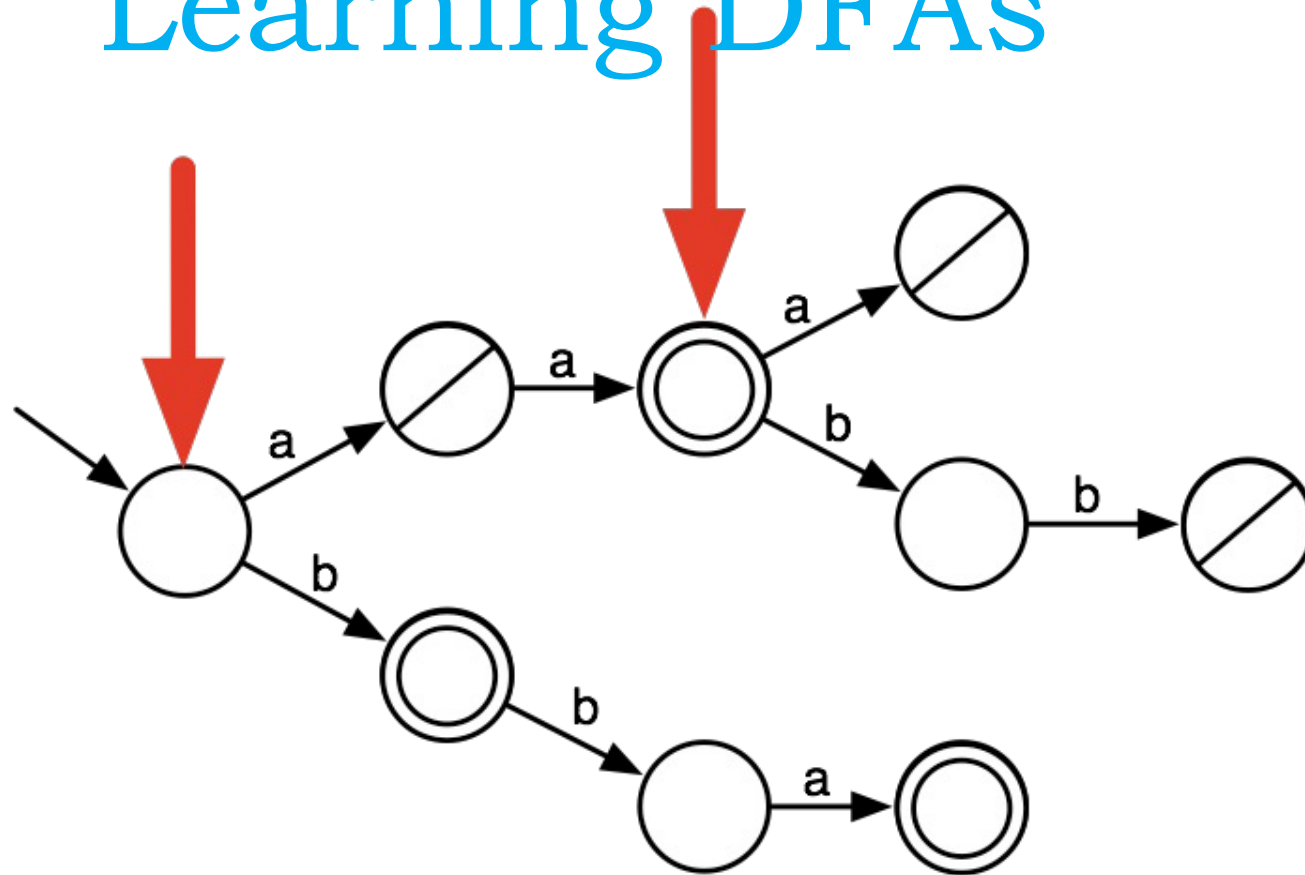
# Learning DFAs



Now we test for **Myhill-Nerode or Markov**:

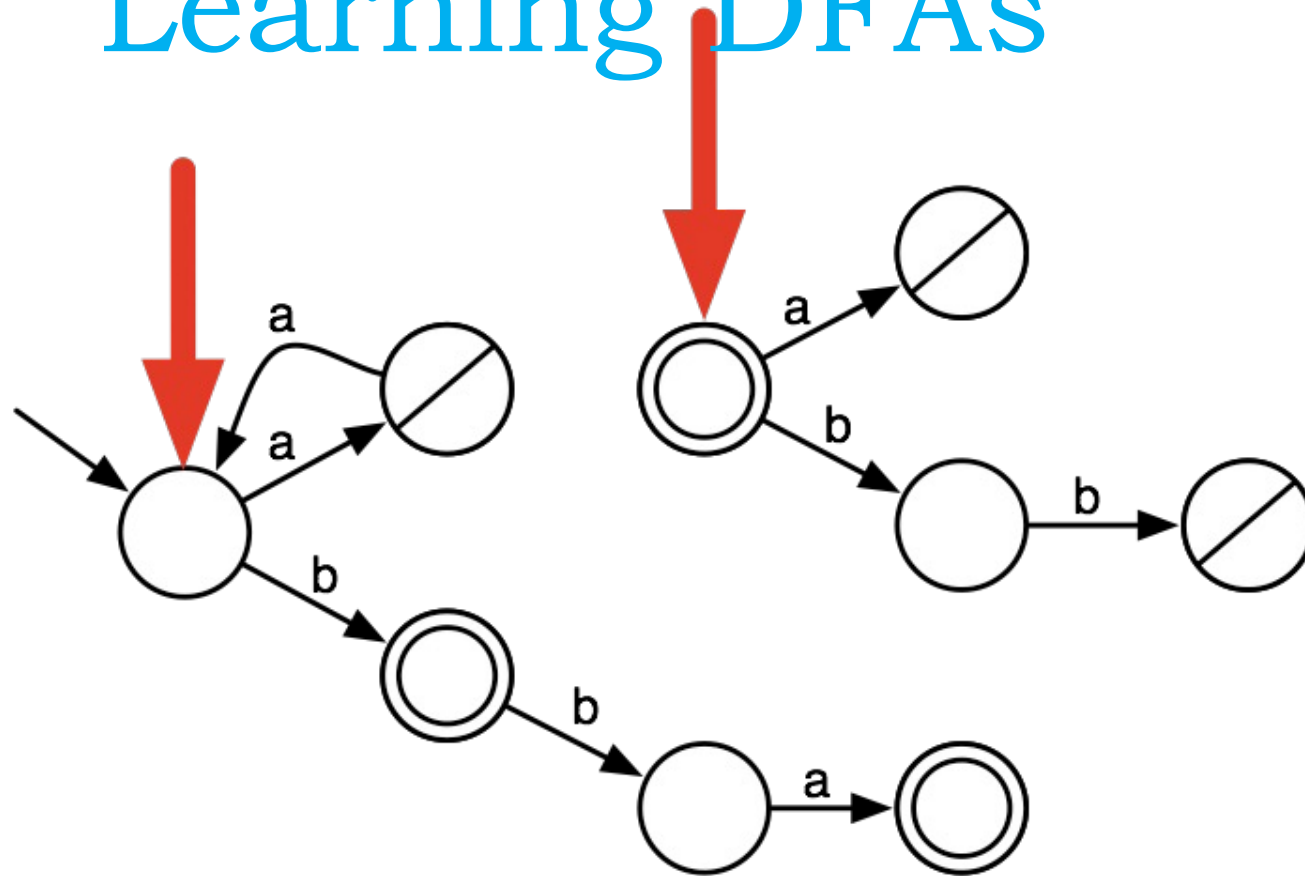
Two states  $q$  and  $q'$  are **equivalent** iff *their future is independent from their past*

# Learning DFAs



**State merging:**  
select two nodes

# Learning DFAs

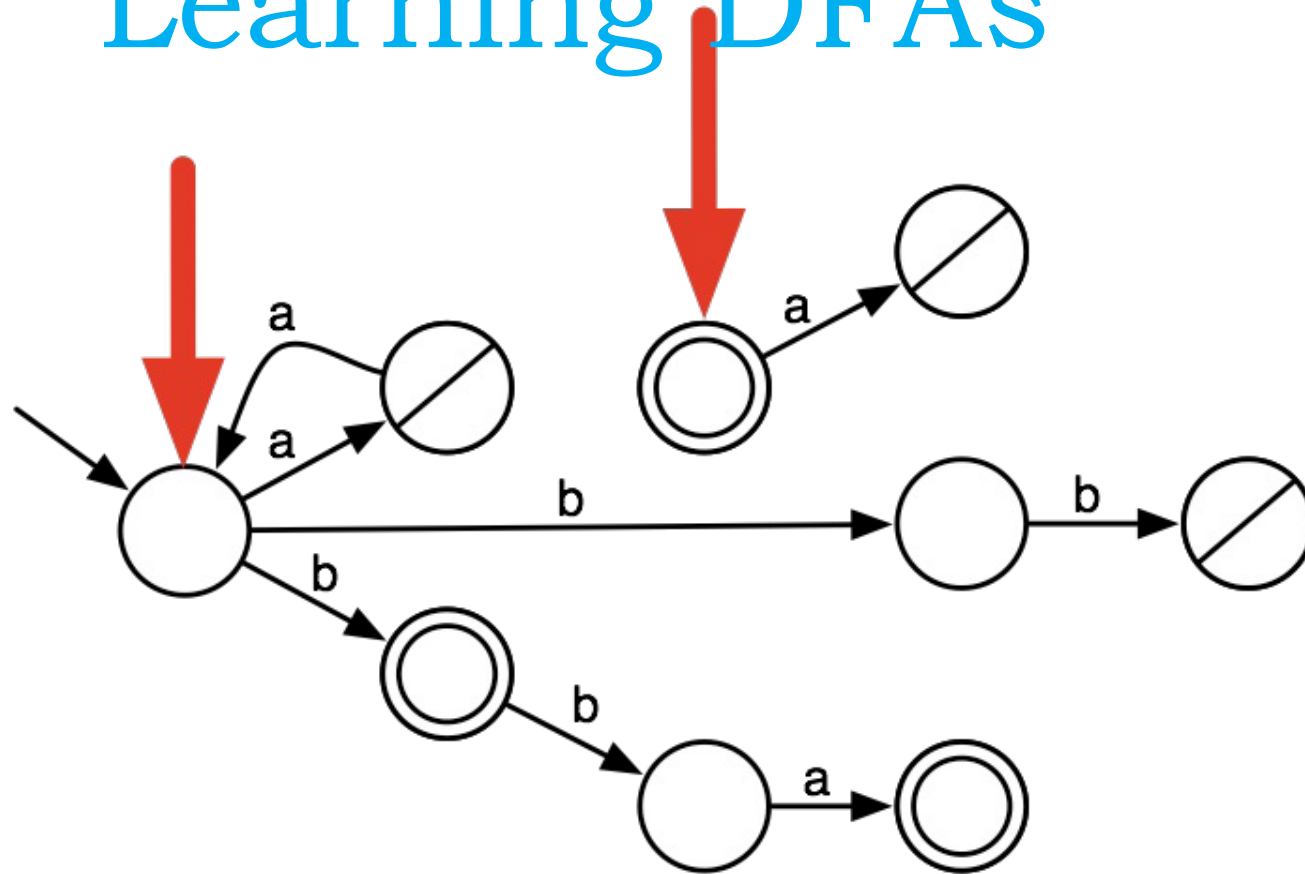


**State merging:**

move **input** transitions from one state to the other



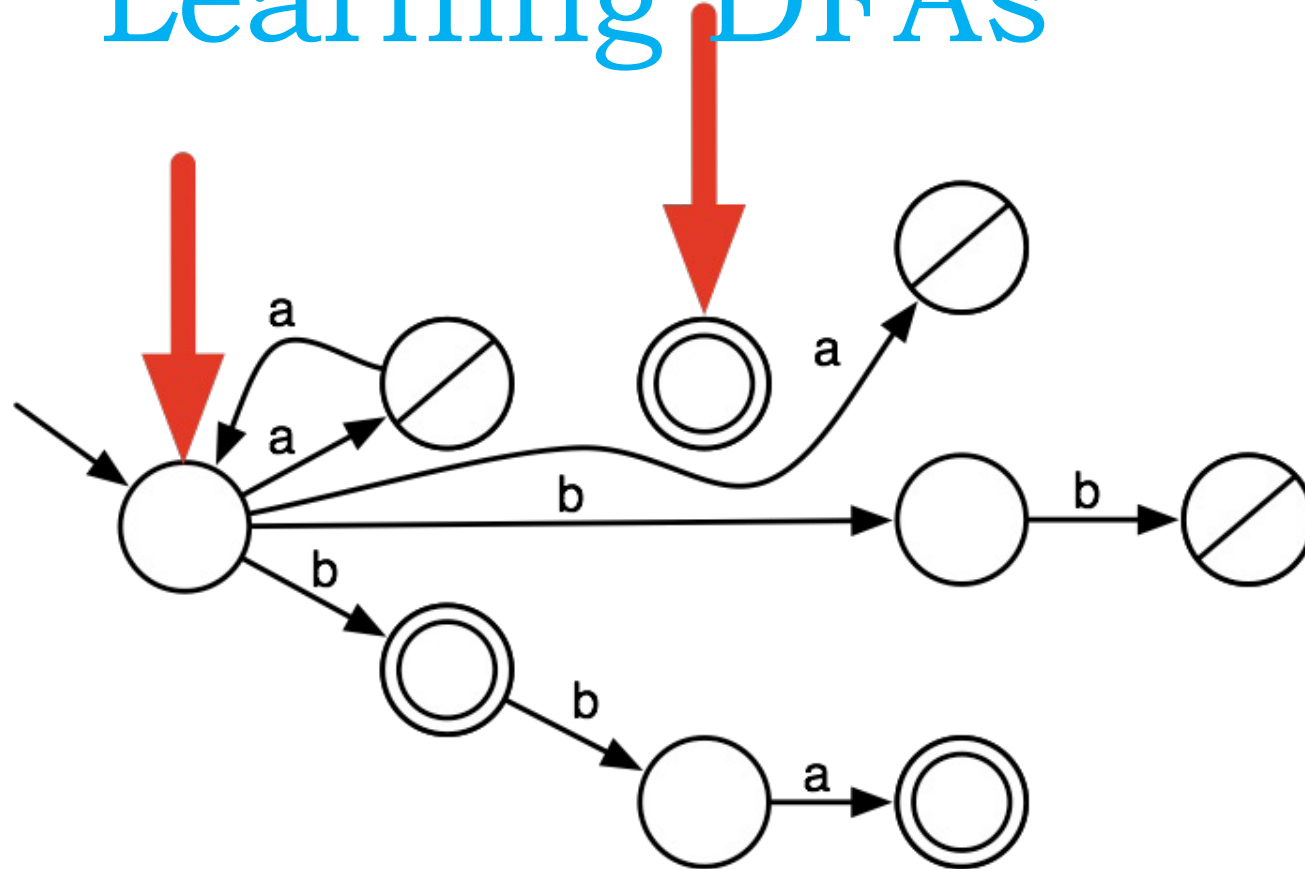
# Learning DFAs



**State merging:**

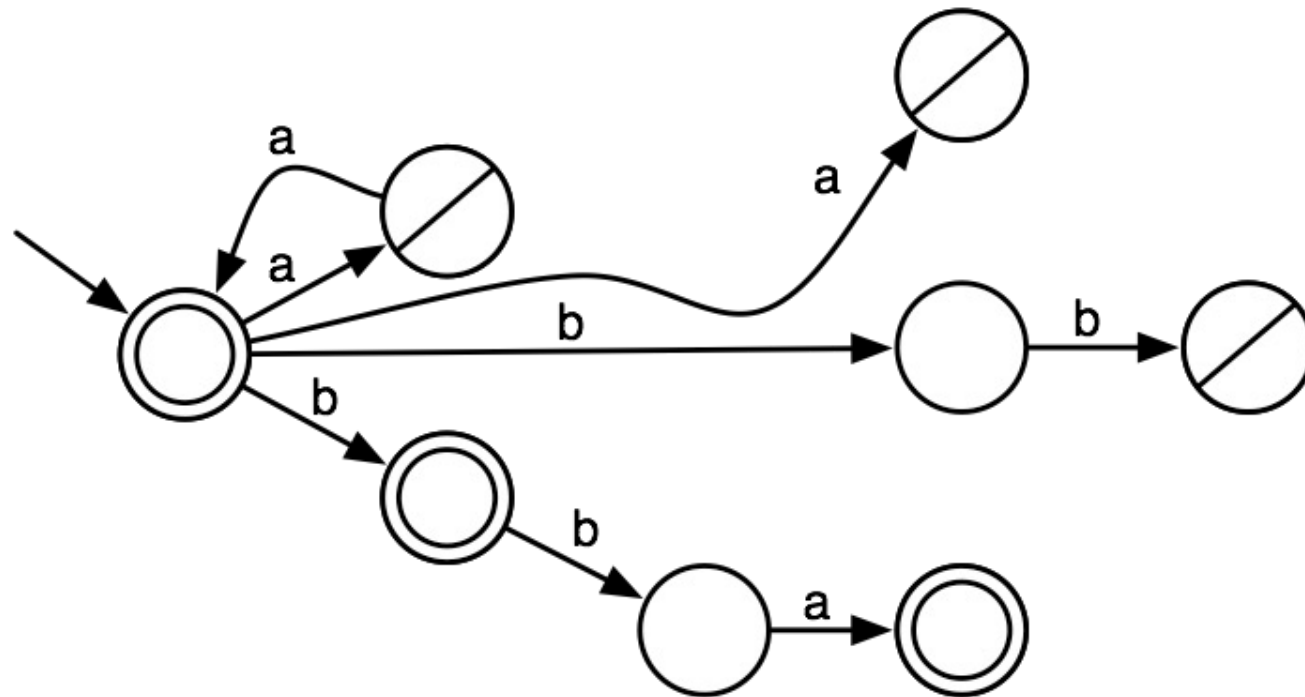
move **input** transitions from one state to the other

# Learning DFAs



**State merging:**  
move **output** transitions

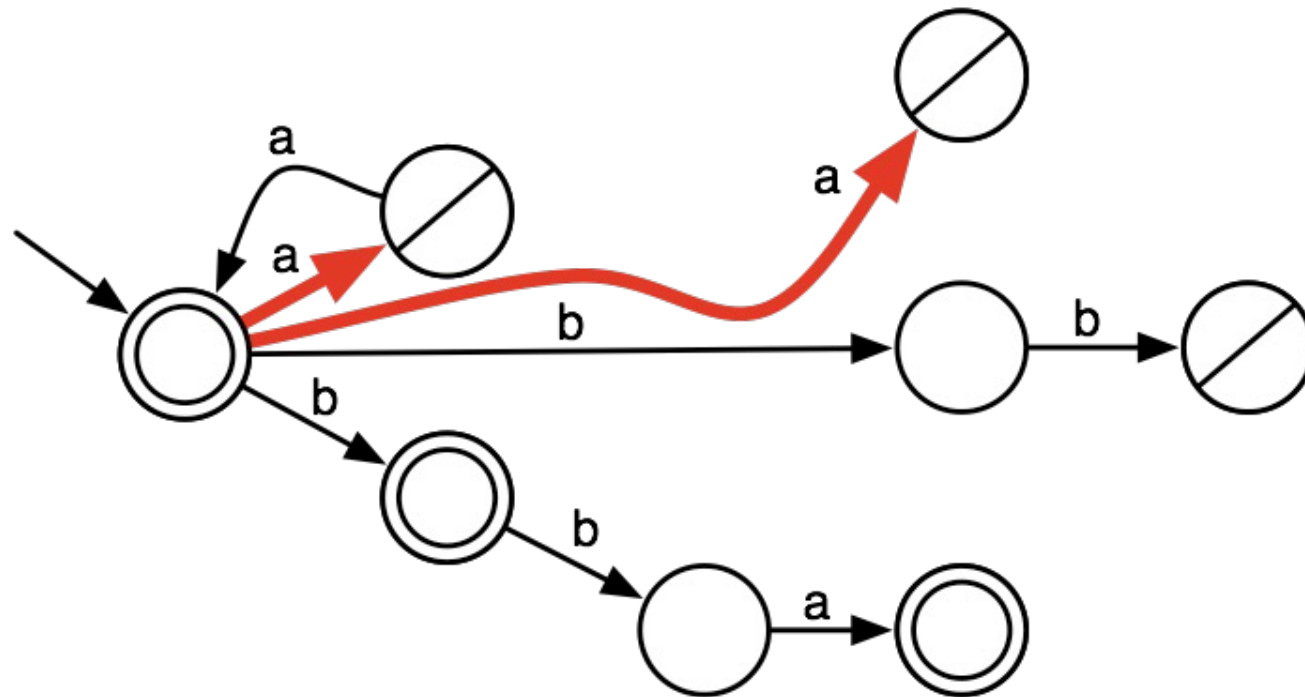
# Learning DFAs



**State merging:**

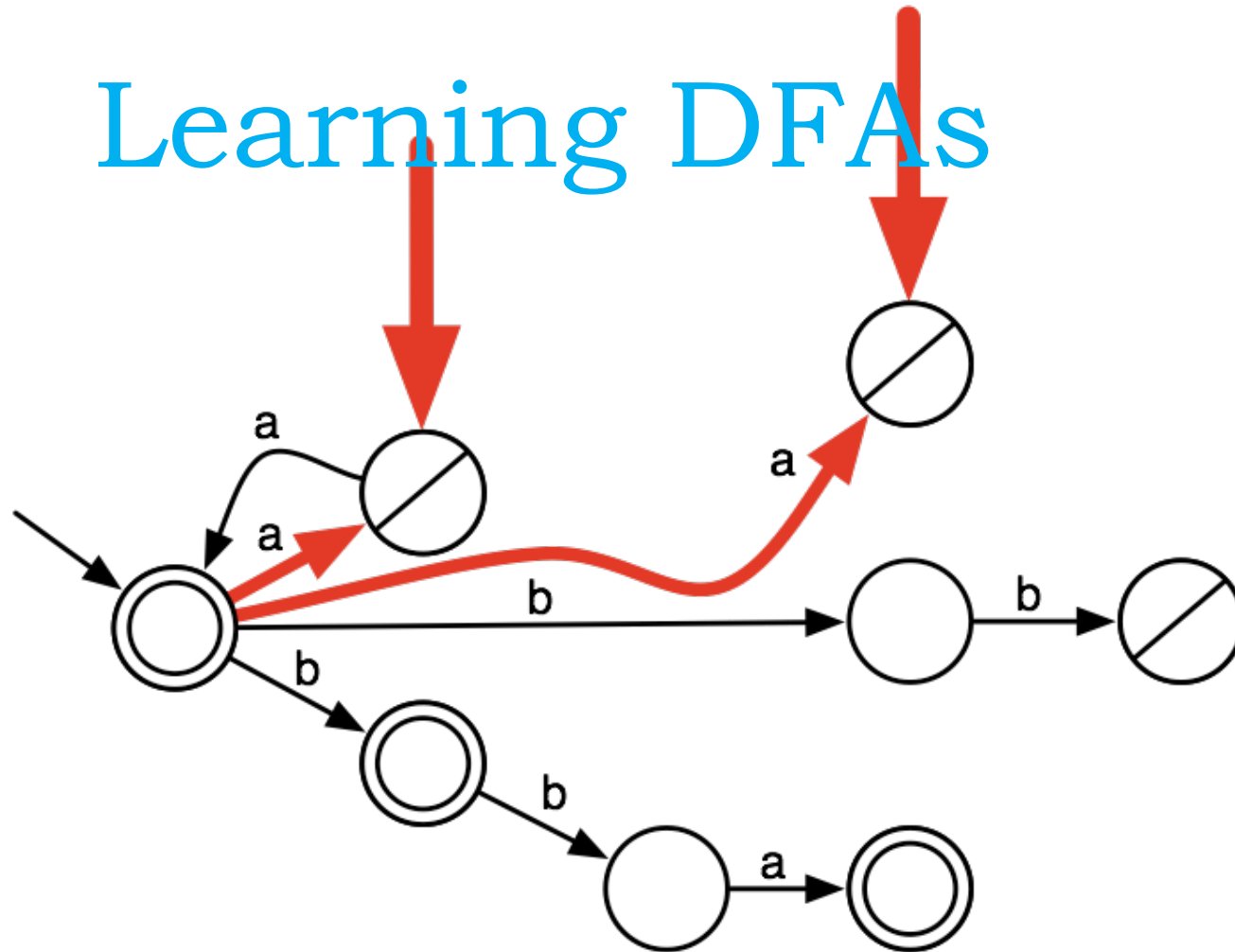
delete the obsolete state, maintain pos/neg

# Learning DFAs



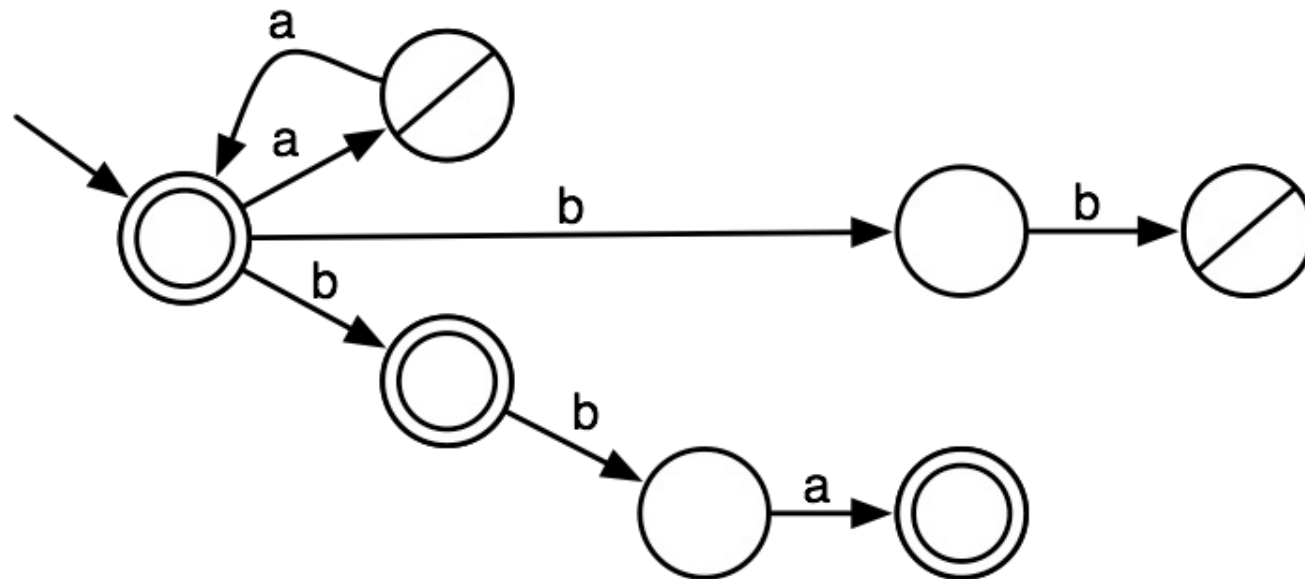
**State merging:**  
merge targets of non-deterministic transitions

# Learning DFAs



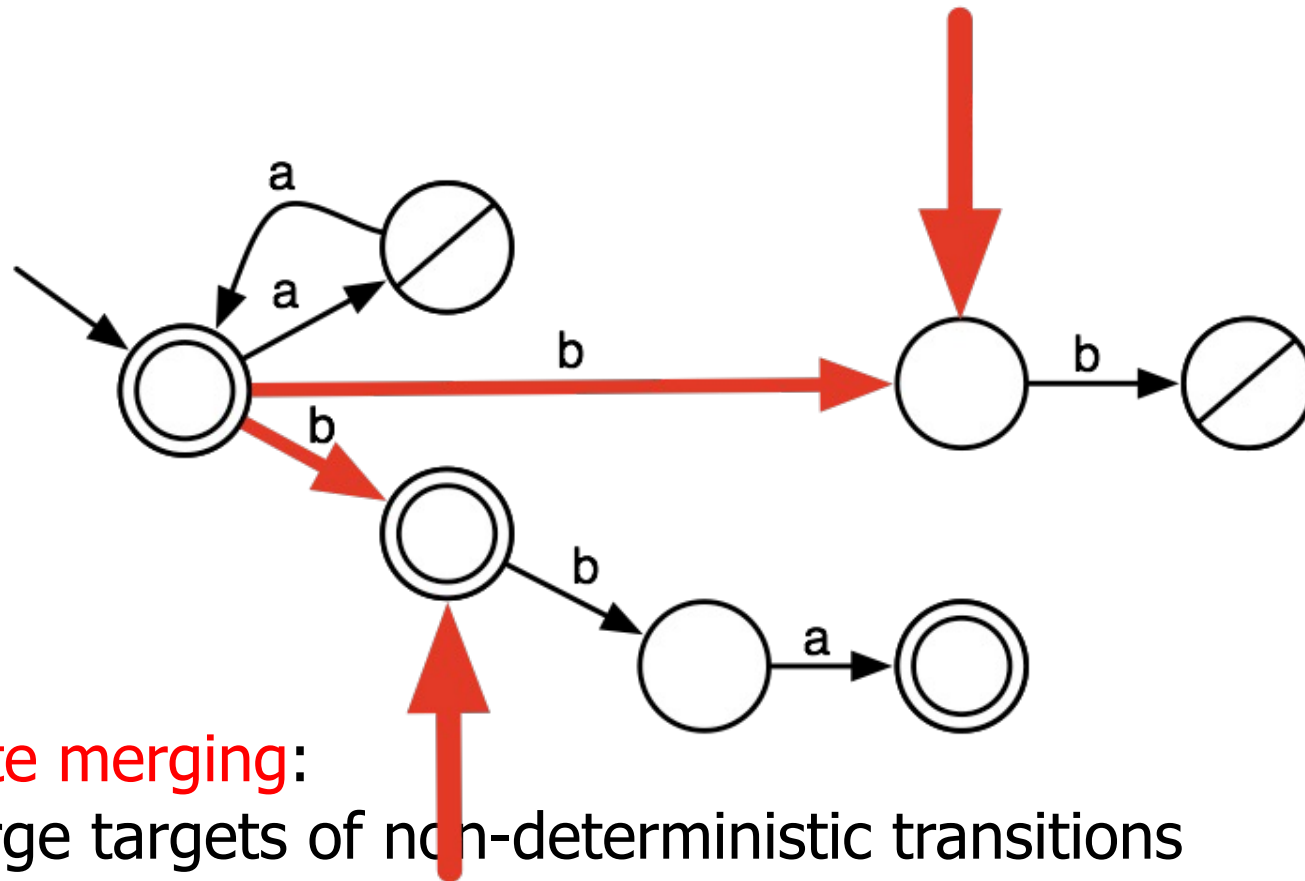
**State merging:**  
merge targets of non-deterministic transitions

# Learning DFAs



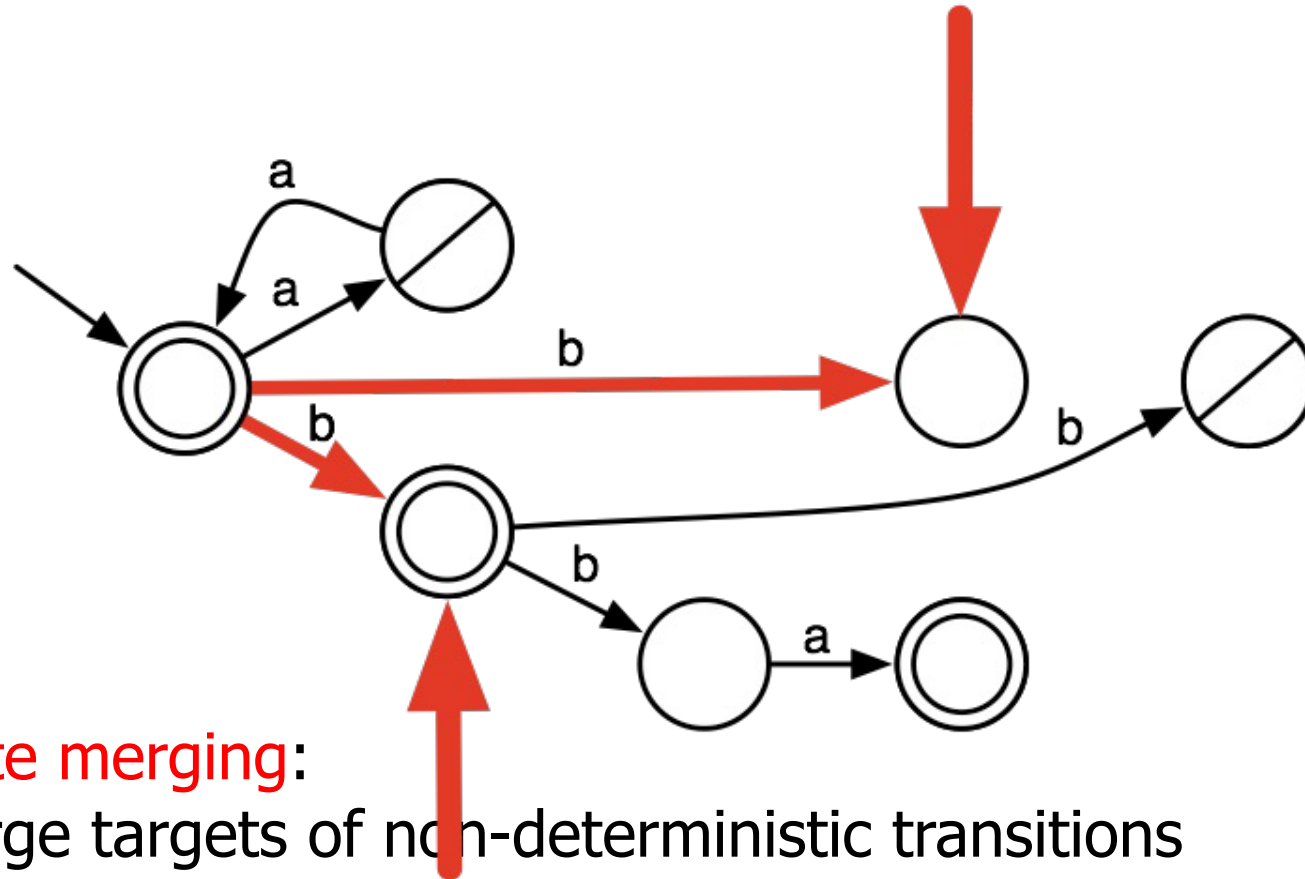
**State merging:**  
merge targets of non-deterministic transitions

# Learning DFAs



**State merging:**  
merge targets of non-deterministic transitions

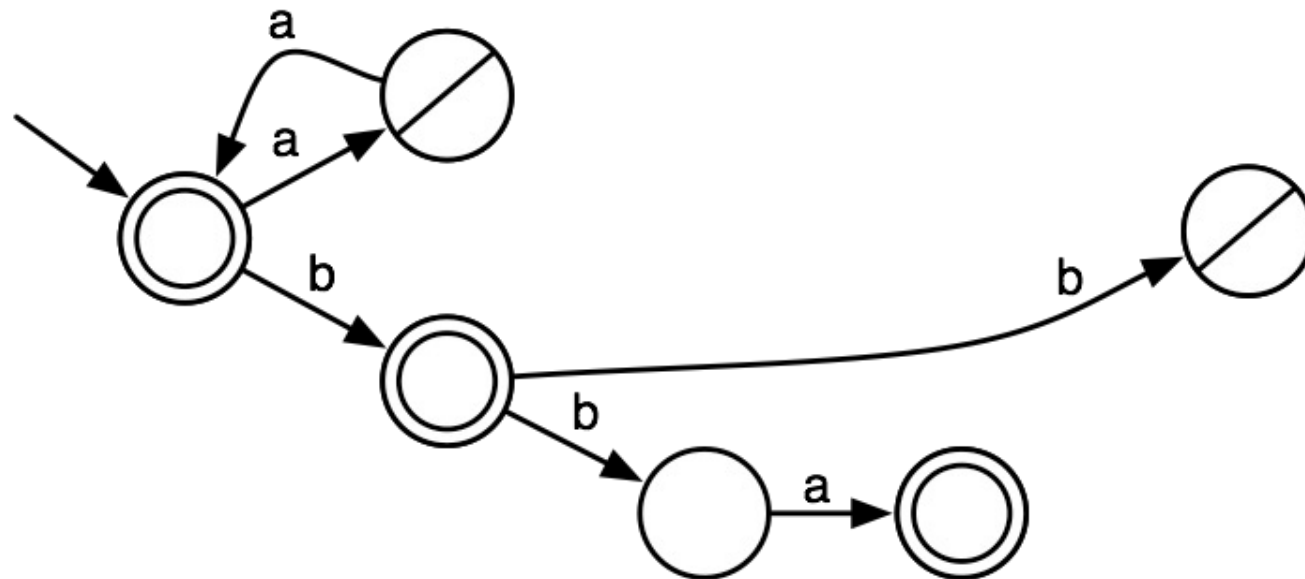
# Learning DFAs



**State merging:**  
merge targets of non-deterministic transitions



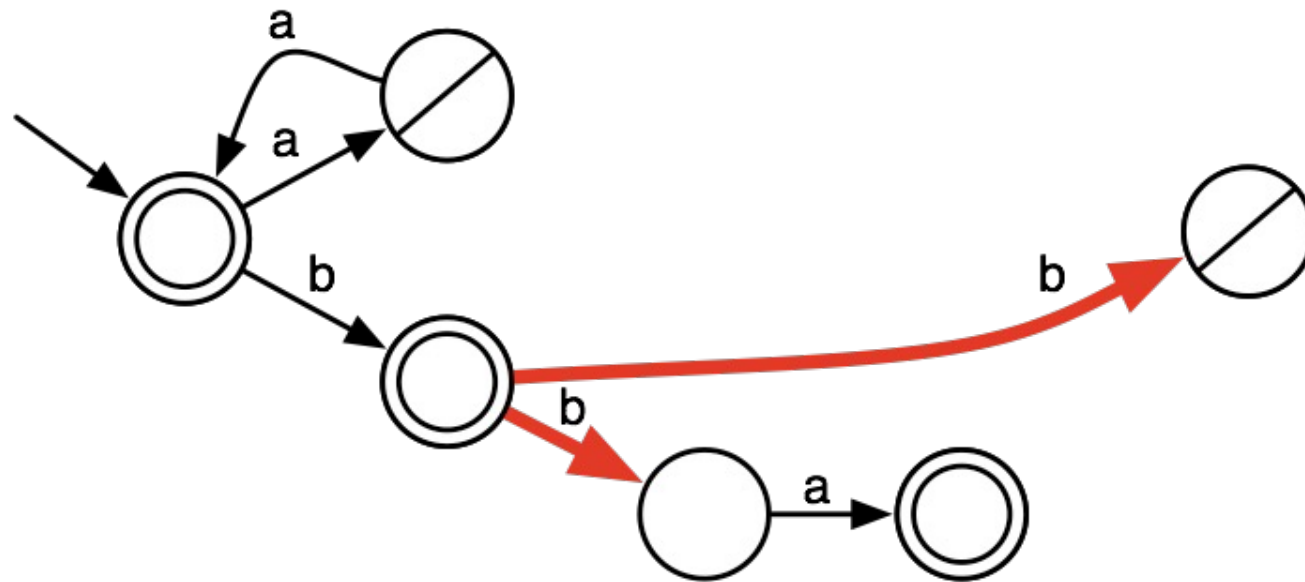
# Learning DFAs



**State merging:**

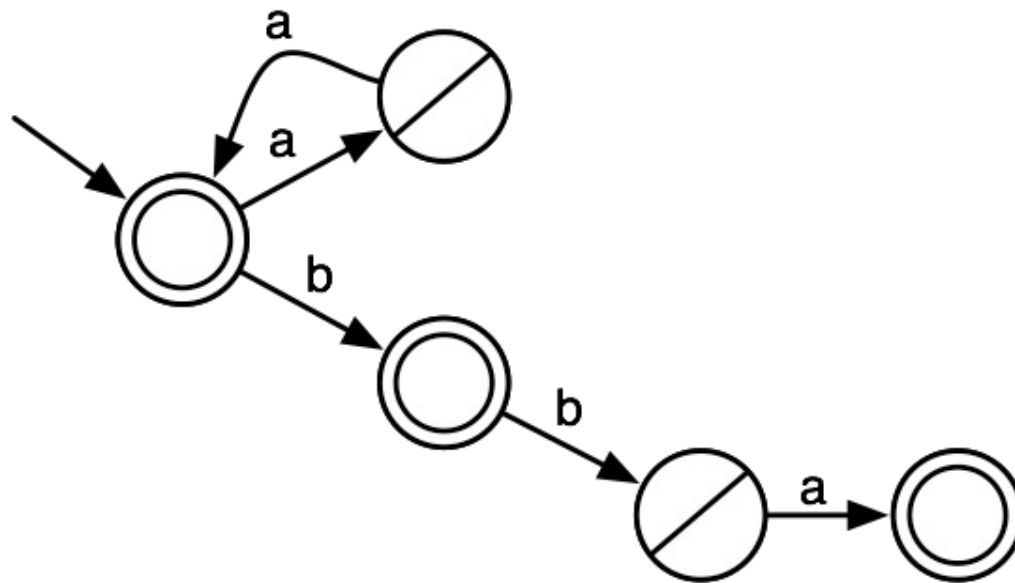
merge targets of non-deterministic transitions

# Learning DFAs



Select two new nodes to merge and **iterate**

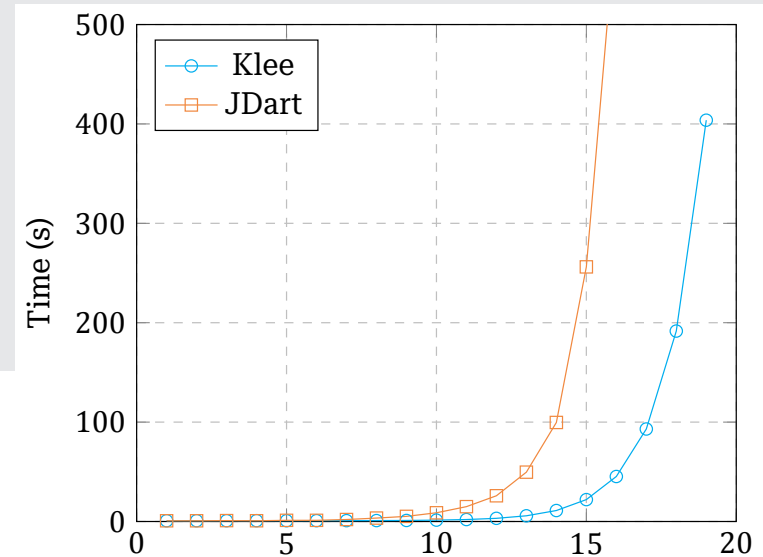
# Learning DFAs



Select two new nodes to merge and **iterate**

# Application: fuzzing loops

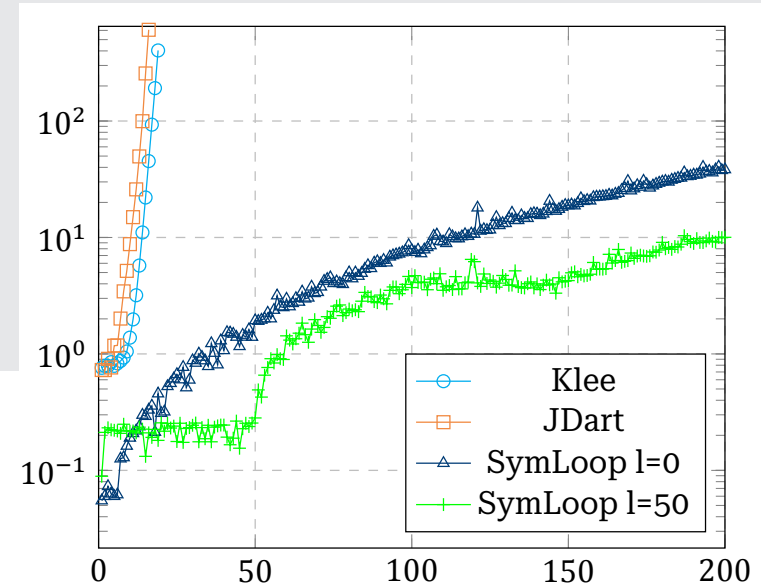
```
1 int main(int argc, char** args) {
2   assert(argc == 3);
3   int limit = atoi(args[1]); // Target to reach
4   int i = 0; // Internal state
5   int j = 0; // Loop variable
6   char symbol; // Character in input
7   char* trace = args[2]; // Input: array of symbols
8
9   while ((symbol = trace[j++]) != 0) { // Get next character in input
10    if (symbol == 'i') {
11      i += 1;
12    } else if (symbol == 'p') {
13      if (i >= limit){
14        assert(0); // Crash
15      }
16    } else {
17      return 0;
18    }
19  }
20  return 0;
21 }
```



with Bram Verboom and Simon Dieck

# Application: fuzzing loops

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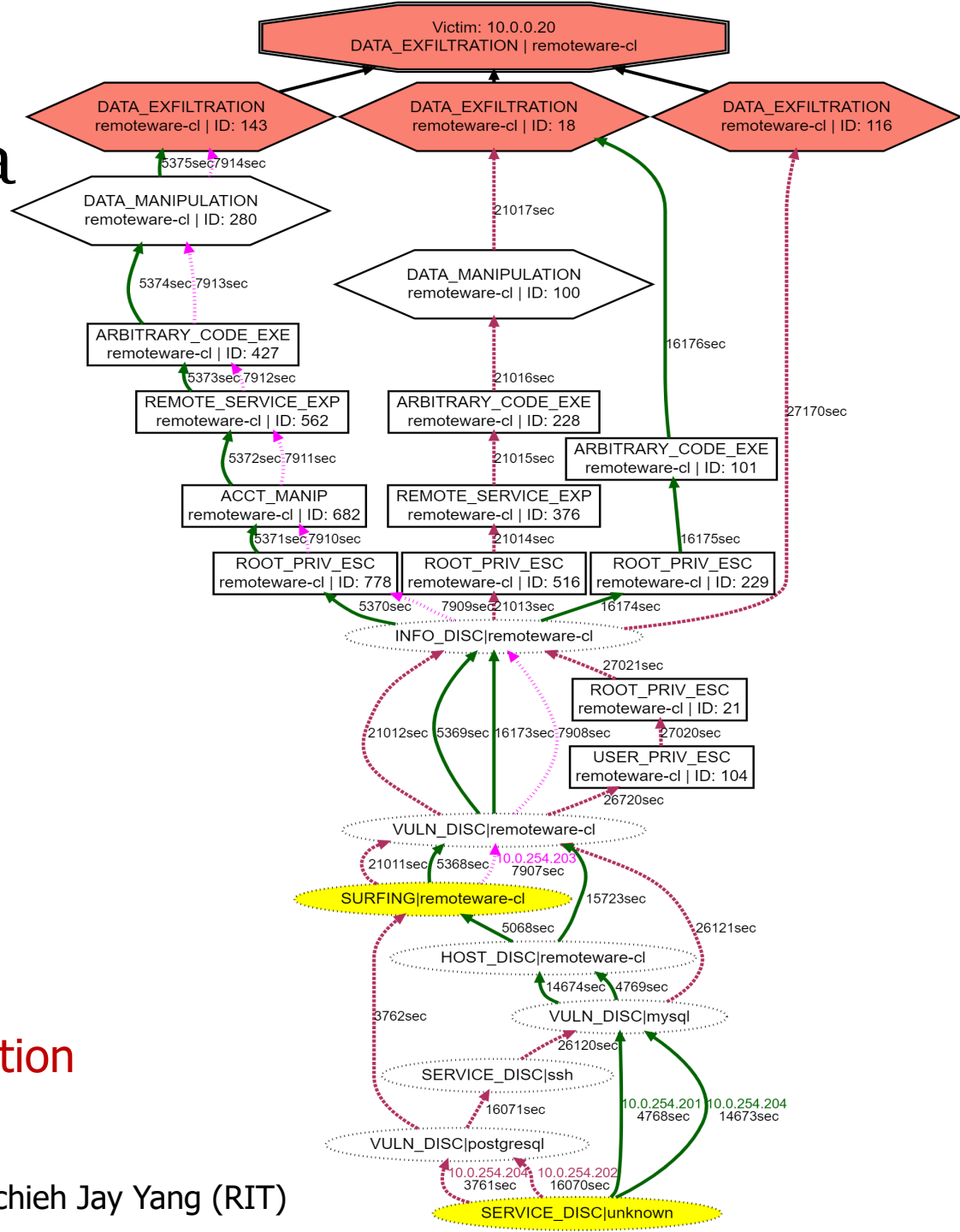
with Bram Verboom and Simon Dieck

# Learning from intrusion data

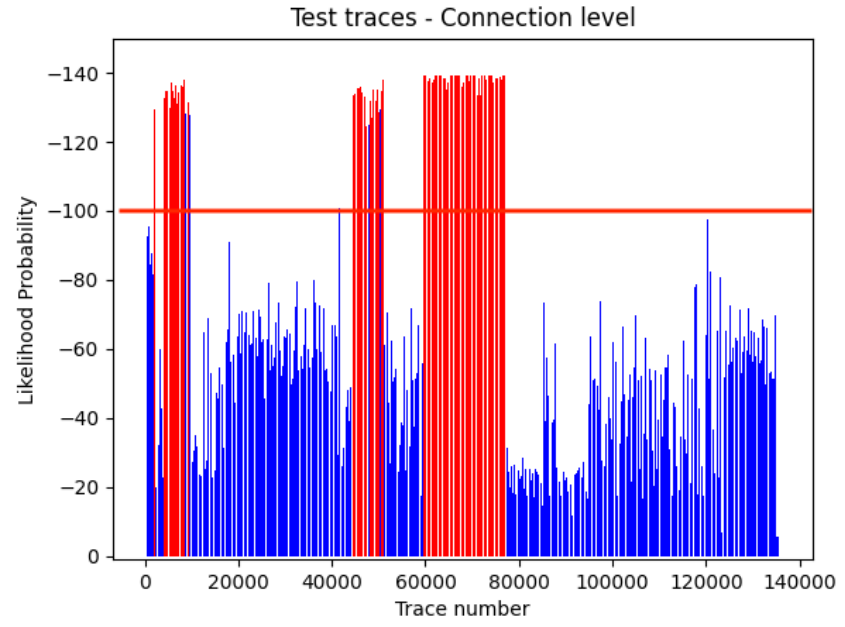
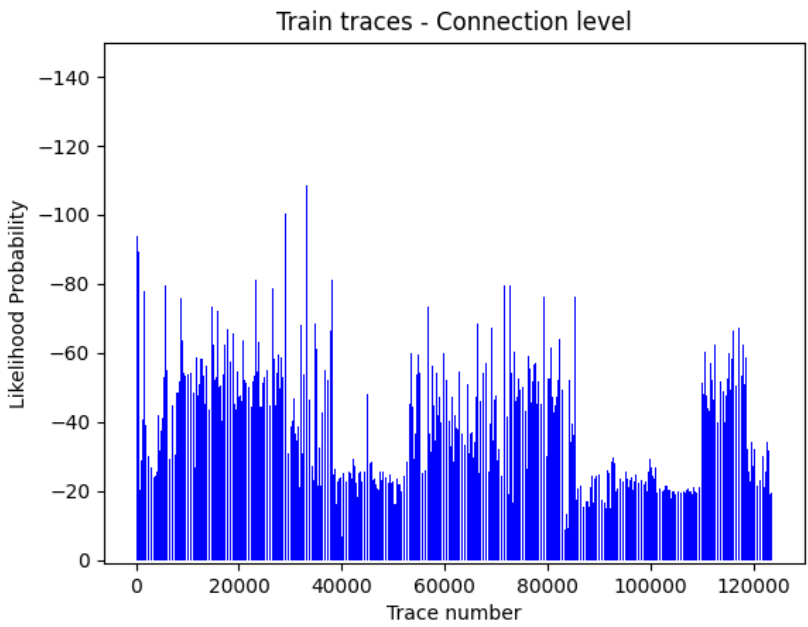
From a learned model, we extract all **paths** leading to **severe objectives**

Paths are time-stamped and colored per attacker

Right: 3 teams showing different ways to reach **data exfiltration**

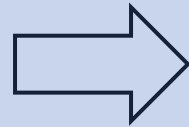


# Detection intrusions from NetFlow

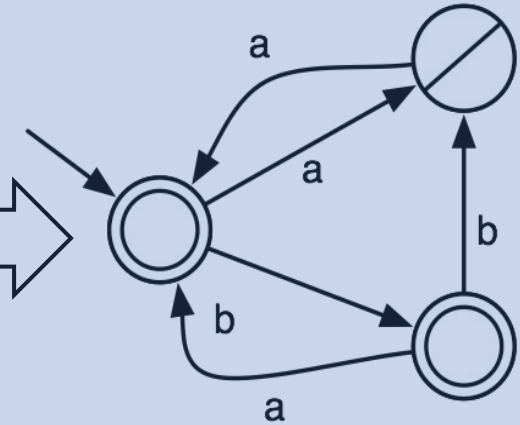
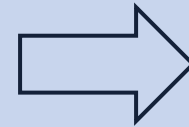


With Clinton Cao

# Active? Work in progress



Passive learner



Active Learner